

KULBIR SINGH AHLUWALIA

[YouTube channel](#) ◊ [GitHub](#) ◊ [LinkedIn](#) ◊ [Google scholar](#)

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EDUCATION

PhD in Computer Science University of Illinois, Urbana-Champaign, USA	<i>June 2022-present</i> GPA: 4/4
Master of Engineering in Robotics University of Maryland, College Park, USA	<i>Aug 2019-May 2021</i> GPA: 3.88/4
B.Tech in Electrical Engineering Punjab Engineering College, India	<i>Aug 2015-May 2019</i> GPA: 8.12/10

EXPERIENCE

Univ. of Illinois, Distributed Autonomous Systems Lab *May 2021-present*
Graduate Research Assistant, **Mentors: Dr Girish Chowdhary & Dr Julia Hockenmaier**

- Building a voice-controlled system to enable users to control a CNC based gardening robot called FarmBot remotely. We are using the Alexa API to make custom Python and Lua scripts for interfacing with the web based application of FarmBot in real-time.
- Working on integrating a pneumatically controlled soft robotic arm with the FarmBot to enable it to clear obstacles and harvest fruits.

Univ. of Maryland, Robotics Algorithms & Autonomous Systems Lab *Jul 2020-Aug 2021*
Independent study ([Report](#)), **Mentor: Dr Pratap Tokekar**

- Processed point clouds of the pasture obtained from the gazebo simulation for selected days of a year using LiDAR mounted on the hector quadcopter controlled using an autonomous navigation script.
- Automated the task of constructing gazebo worlds for grass pastures where each plant has a unique pose and is scaled to match real world height data of a location.

University of Waterloo, Ontario, Canada *Mar-Jul 2018*
Visiting Scholar ([Report](#)), **Mentor: Dr Simarjeet Saini**

- Developed an orange sweetness detector which used scaled conjugate gradient backpropagation in MATLAB to non-destructively predict sweetness of oranges with an accuracy of 70%. Discrete cosine transform was used to reduce dimensions of input matrix and prevent memory overflow.
- Designed prototypes in Solidworks, which were 3D printed using the Ultimaker 3. Developed low-cost photonic devices like Urea in milk detector and the Fundus eye camera. The Fundus eye camera used Raspberry Pi3 to capture images and videos of the retina of a model eye to aid in diagnosis of diseases.

Indian Institute of Technology, Roorkee *Jun-Jul 2016*
Research Intern ([Report](#)), **Mentor: Dr Dharmendra Singh**

- Varied the thickness of radio wave absorbers such as nickel ferrite on a UAV model and its individual parts like cylindrical body, spherical nose and cuboidal wings and detected its effect on the Radar Cross Section in Ansys HFSS.

RESEARCH PAPERS

- Rangwala, M.; Liu, J.; **Ahluwalia, K.S.**; Ghajar, S.; Dhami, H.S.; Tracy, B.F.; Tokekar, P.; Williams, R.K. DeepPaSTL: Spatio-Temporal Deep Learning Methods for Predicting Long-Term Pasture Terrains Using Synthetic Datasets. *Agronomy* 2021, 11, 2245. (published in *Agronomy* as part of the Special Issue *AI and Agricultural Robots*) [[Link to published paper](#)] [[PDF](#)]
- Liu, J.; Rangwala, M.; **Ahluwalia, K.S.**; Ghajar, S.; Dhami, H.S.; Tracy, B.F.; Tokekar, P.; Williams, R.K. “Intermittent Deployment for Large-Scale Multi-Robot Forage Perception: Data Synthesis, Prediction, and Planning”, 2021. [[arXiv](#)] [[PDF](#)] (under review at *IEEE Transactions on Automation Science and Engineering*)

RESEARCH ARTICLE

- The multispectral Fundus Eye camera prototype was featured in the Optics and Photonics News (OPN) in February 2019 in “Saini, Simarjeet Singh, Aneesh Sridhar, and Kulbir Ahluwalia. “[Smartphone optical sensors.](#)” Optics and Photonics News 30, no. 2 (2019): 34-41.” [\[Link to article\]](#) [\[PDF\]](#)

CONFERENCE PRESENTATION

- Yuqi Li, Kulbir S. Ahluwalia, and Simarjeet S. Saini. “[Reinforcement learning integrated with supervised learning for training of near infrared spectrum data for non-destructive testing of fruits.](#)” In Sensing for Agriculture and Food Quality and Safety XII, vol. 11421, p. 114210J. International Society for Optics and Photonics, 2020. [\[Link to conference presentation\]](#)

TECHNICAL SKILLS

Languages	Python, MATLAB, C++, Lua
Analysis & Design	Simulink, Blender, AutoCAD, Solidworks, Ultimaker Cura, Adobe Premiere Pro
Libraries	Numpy, Pandas, OpenCV, PyTorch, SciPy, Requests
Other	ROS, Gazebo, RViz, CUDA, Linux, Docker, Git, Doxygen, Anaconda, LaTeX

COURSEWORK

Graduate: Mobile Robotics, Autonomous robotics, Decision making for robotics, Visual Learning and recognition, Planning for Autonomous Robots, Perception for Autonomous Robots, Control of Robotic systems, Robot modelling, Robot programming, Building Robot software systems.

Undergraduate: Neural networks and fuzzy systems, Advanced control systems, Microprocessors and interfacing, Power electronics, Mechatronics, Engineering analysis and design, Manufacturing, Biomedical engineering, Electromagnetic theory, [Python Programming](#).

PROJECTS

[SLAM from 2D LiDAR data using split and merge line extraction algorithm](#) *Dec 2021*

[State estimation using Extended Kalman Filter for GPS+IMU+Encoder sensor fusion](#) *Nov 2021*

[Processed data from RTK-GPS, IMU and encoders to plot trajectory of a field robot](#) *Sep 2021*

[Autonomous Vaccine Delivery Robot](#) *May 2021*

- Designed an autonomous robot capable of navigating and localizing itself in a test arena using QR codes and arrows. It used a RGB camera, IMU, optical encoders and an ultrasonic sensor to detect, retrieve and transport user specified blocks from a collection zone to a drop-off zone. [\[Featured semester video\]](#) [\[Robot videos\]](#) [\[Featured post\]](#)

[Image segmentation using superpixels](#) *Dec 2020*

- Built a segmentation network using SLIC superpixels as input. A pretrained VGG16 network is used with its last few layers replaced by fully connected layers to classify superpixels into classes. (Accuracy 98%)

[Persistent-Monitoring using Multi-Robot \(UAV-UGV\) Coordination](#) *Dec 2020*

[Optimized a GestureGAN for resource constrained settings](#) *Dec 2020*

- Used MobileNet to optimize cross-view image generation with a 5.7X reduction in parameters.

[Self-adjusting roadmaps](#) - Navigation in unknown environments using LD-PRM. *May 2020*

[Estimated the motion of a car using Visual odometry](#) *May 2020*

[Color segmentation using Gaussian mixture models & Expectation maximization](#) *April 2020*

[Image Classification using CNN](#) *May 2020*

[AR-Tag detection](#) - superimposed an image and virtual cube on an AR tag. *March 2020*

[Tracked moving objects using Lucas-Kanade Tracker](#) *April 2020*

Baxter transporting cubes in Gazebo

April 2020

- Simulated a Baxter robot transporting cubes from one table to another in Gazebo using ROS Kinetic. The waypoints for moving the baxter arm were found out using Rviz. The gazebo world had custom designed obstacles which were avoided by the baxter arm.

Implemented A star algorithm for Path Planning on Turtlebot 3

May 2020

- Implemented the A* algorithm for the Turtlebot 3 in a configuration space with obstacles. The Turtlebot 3 is bound by non holonomic constraints while the action set consists of 8 combinations of two user-defined RPMs.

Path planning for point and rigid robot using Dijkstra's Algorithm

April 2020

Lane detection and Turn prediction for self driving car

March 2020

- Developed an algorithm that used hough transform and histogram of lanes approach.
- Implemented homography and warp perspective functions from scratch to create overlays.

Agile Robotics for Industrial Automation Competition (ARIAC) 2019

May 2020

- Developed an industrial system consisting of UR 10 robotic arms, conveyor belts and Autonomous Ground Vehicles (AGVs).
- Enabled the system to pick required parts from the conveyer belt, dispose faulty parts, assemble orders and deliver them using AGVs.

Designed a PID controller for Turtlebot 3

April 2020

Modelled a UR 5 arm with Parallel Gripper in Rviz

Sep-Dec 2019

- Simulated a 7 DOF UR5 arm using Moveit and Rviz. Calculated the DH parameters, computed forward kinematics manually and verified the results using the Peter Corke Robotics toolbox in MATLAB.

[\[Simulation videos\]](#)

Designed a LQR and LQG controller - for two inverted pendulums on a moving cart.

Dec 2019

Teleoperated gesture controlled robotic arm

Aug 2018-May 2019

- Engineered a prototype capable of transporting objects from one room to another using web-based remote access with live video feed and a gesture controlled robotic arm. With on-board power supply and a bright custom designed constant current LED light source, our robot was able to navigate through low light areas.
- The robot could be controlled using any smart device and also had a speaker to play prerecorded messages to interact with people around the robot.

Pick n place transporter bot - First Prize in IIT Roorkee; 6th/400 teams at IIT Bombay. Aug-Dec 2016

Smart Garden - First Prize in Texas Instruments Hardware Hackathon.

March 2017

LEADERSHIP AND TEACHING EXPERIENCE

- Served as **Technology Head for Hardware domain** for IEEE PEC Student branch. Conducted workshops on making a “Pick n Place Transporter Robot” and “Using the Raspberry Pi” to share our team’s experiences and techniques with our juniors in PEC.
- Taught Math and Science to government high school students as part of “PUNARKRITI Welfare Society” (Jan-Apr 2016) and “Junior Einstein” (Dec 2018) social welfare organizations.

OTHER ACHIEVEMENTS AND AWARDS

- Participant in the team from UIUC selected in the Top 10 for Amazon Alexa SimBot challenge.
- First prize in MAJOR PROJECT in the B.Tech. Examination of Electrical Engineering, 2015-19 for “Teleoperated Gesture controlled Robotic arm”.
- Received Certificate of Appreciation for contributions to IEEE PEC twice. (Aug 2017, 2018)
- Awarded with the **National Bal Shree Award in Creative Scientific Innovations** by the Ministry of Human Resource Development, Govt. of India conferred by the President of India.